## **ACT Configuration**

P,PI and PID temperature

controls using the CHR method

info@delorenzo.it. WITH SOFTWARE for data aquisition WITHOUT SOFTWARE modules. CONTROLLERS PROCESSES CONTINUOS AUTOMATIC CONTROL DISCONTINUOS AUTOMATIC CONTROL P type P controller P control, P type process 2 position controllers, 3 range controllers I type I controller P control, first and higher order processes Sampling acquisition techniques I2 type D controller Second order I control, I type processes 2 position controller, first order process First Order PI controller P,PD,PI,PID controls, high order process 3 range controller, second order process Higher than first PD controller Ziegler-Nichols dynamic method 2 position controller, delayed feedback, second order process Second Order with PID controller Chien-Hrones-Reswick static method 2 position controller, elastic feedback, second dead time order process Parallel and series configuration PID controller with gain and offset adjust Sampling control, fourth order process APPLICATIONS CONTROL OF A DC MOTOR TEMPERATURE CONTROL LEVEL CONTROL 2 position controller P,PI,and PID speed controls Automatic level control with P,PI using the CHR method and PID controllers 2 position controller, delayed Control of a generator feedback 2 position controller, elastic ■ FLOW CONTROL feedback LIGHT CONTROL 3 range controller

P,PI,and PID light controls

using the CHR method

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Automatic flow-through control

with P,PI and PID controllers

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